ROHM

STRUCTURE   Silicon monolithic integrated circuits

PRODUCT SERIES   Bipolar stepping motor driver

TYPE   **BD6775EFV**

FUNCTION   · PWM constant current controllable H bridge driver

                     · DMOS output

○Absolute maximum ratings (Ta=25℃)

Parameter	Symbol	Limit	Unit
Supply voltage	VCC	7	V
	VM	40	V
Power dissipation	Pd	1100[*1]	mW
Input voltage for control pin	VIN	0~VCC	V
Maximum output current	IOUT	800[*2]	mA
Operating temperature range	Topr	-20~+75	℃
Storage temperature range	Tstg	-55~+150	℃
Junction temperature	Tjmax	150	℃

[*1] 70mm × 70mm × 1.6mm glass epoxy board. Derating in done at 8.8mW/℃ for operating above Ta=25℃.
[*2] Do not, however exceed Pd, ASO and Tjmax=150℃.

○Recommended operating conditions (Ta=-20~+75℃)

Parameter	Symbol	Min	Typ	Max	Unit
Supply voltage	VCC	4.5	5.0	6.0	V
	VM	10	35	37	V
Output current	IOUT	-	-	500[*3]	mA

[*3] Do not, however exceed Pd, ASO.

This product described in this specification isn't judged whether it applies to COCOM regulations.
Please confirm in case of export.
This product isn't designed for protection against radioactive rays.

Rev.B

○Electrical characteristics (Unless otherwise specified, Ta=25℃, VCC=5.0V, VM=35V)

Parameter	Symbol	Limit			Unit	Conditions
		Min	Typ	Max		
Overall						
VCC Circuit current during standby mode	ICCST	250	360	400	μA	PS=0V, VREF=2V
VCC Circuit current	ICC	4.4	5.8	7.2	mA	PS=H, VREF=2V
VM circuit current during standby mode	IVMST	-	0	10	μA	PS=0V, VREF=2V
VM circuit current	IVM	2	3	4	mA	PS=H, VREF=2V
Power-save						
High level input voltage	VPSH	2.0	-	-	V	
Low level input voltage	VPSL	-	-	0.8	V	
High level input current	IINH	25	50	80	μA	VIN=5V
Low level input current	IINL	5	10	16	μA	VIN=1V
Control input						
High level input voltage	VINH	2.0	-	-	V	PHA1, PHA2, I01, I11, I02, I12
Low level input voltage	VINL	-	-	0.8	V	〃
Output						
Output on resistance	RON	-	3	3.6	Ω	IOUT=±300mA, on high and low sides in total
Output leak	ILEAK	-	0	10	μA	
Current control block						
RNFX inflow current	IRNF	-2	-0.6	-	μA	RNF=0V
VREFX inflow current	IVREF	-1	-0.1	-	μA	VREF=0V
VREFX voltage range	VREF	0	-	2.0	V	
Comparator threshold 100%	CTHLL	0.34	0.4	0.46	V	VREF=2V, I0x=L, I1x=L
Comparator threshold 67%	CTHHL	0.227	0.267	0.307	V	VREF=2V, I0x=H, I1x=L
Comparator threshold 33%	CTHLH	0.113	0.133	0.153	V	VREF=2V, I0x=L, I1x=H
Minimum on time	TMINON	0.3	0.5	1.0	μS	R=39kΩ, C=1000pF, output 100Ω load

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○Package outline

BD6775EFV

Product No.

Lot No.
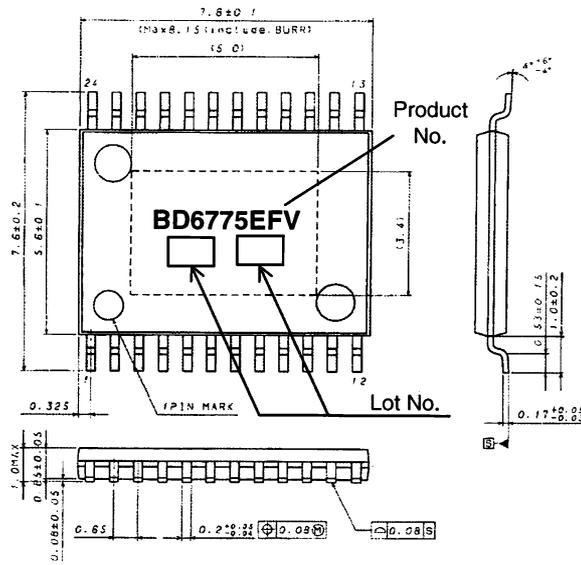
HTSSOP-B24 (Unit:mm)

○Block diagram
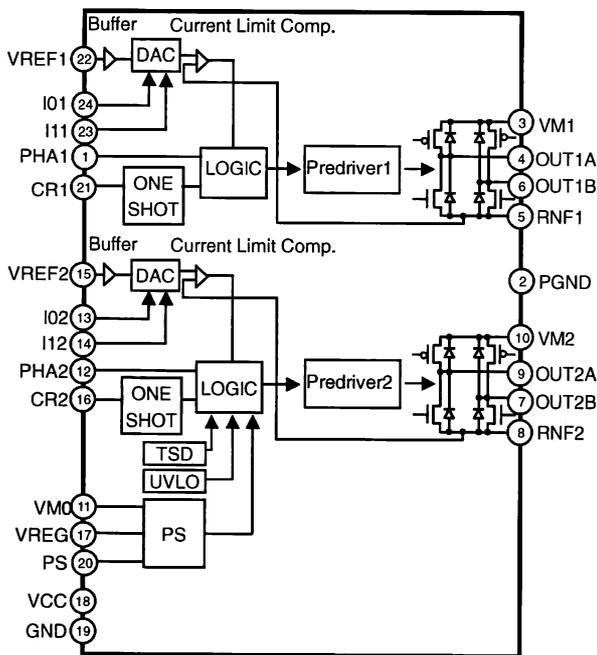
○Pin No. / Pin name

Pin No.	Pin name
1	PHA1
2	PGND
3	VM1
4	OUT1A
5	RNF1
6	OUT1B
7	OUT2B
8	RNF2
9	OUT2A
10	VM2
11	VM0
12	PHA2
13	I02
14	I12
15	VREF2
16	CR2
17	VREG
18	VCC
19	GND
20	PS
21	CR1
22	VREF1
23	I11
24	I01

Rev.B

○Operation Notes

(1) Absolute maximum ratings

Use of the IC in excess of absolute maximum ratings such as the applied voltage or operating temperature range (Topr) may result in IC damage. Assumptions should not be made regarding the state of the IC (short mode or open mode) when such damage is suffered. The implementation of a physical safety measure such as a fuse should be considered when use of the IC in a special mode where the absolute maximum ratings may be exceeded is anticipated.

(2) Power supply lines

Regenerated current may flow as a result of the motor's back electromotive force. Insert capacitors between the power supply and ground pins to serve as a route for regenerated current. Determine the capacitance in full consideration of all the characteristics of the electrolytic capacitor, because the electrolytic capacitor may loose some capacitance at low temperatures. If the connected power supply does not have sufficient current absorption capacity, regenerative current will cause the voltage on the power supply line to rise, which combined with the product and its peripheral circuitry may exceed the absolute maximum ratings. It is recommended to implement a physical safety measure such as the insertion of a voltage clamp diode between the power supply and GND pins.

(3) Ground potential

Ensure a minimum GND pin potential in all operating conditions.

(4) Setting of heat

Use a thermal design that allows for a sufficient margin in light of the power dissipation (Pd) in actual operating conditions.

This IC exposes its frame of the backside of package. Note that this part is assumed to use after providing heat dissipation treatment to improve heat dissipation efficiency. Try to occupy as wide as possible with heat dissipation pattern not only on the board surface but also the backside.

(5) Actions in strong magnetic field

Use caution when using the IC in the presence of a strong magnetic field as doing so may cause the IC to malfunction.

(6) ASO

When using the IC, set the output transistor for the motor so that it does not exceed absolute maximum ratings or ASO.

(7) Thermal shutdown circuit

This IC incorporates a TSD (thermal shutdown) circuit (TSD circuit). If the temperature of the chip reaches the following temperature, the motor coil output will be opened.The thermal shutdown circuit (TSD circuit) is designed only to shut the IC off to prevent runaway thermal operation. It is not designed to protect the IC or guarantee its operation. Do not continue to use the IC after operating this circuit or use the IC in an environment where the operation of this circuit is assumed.

TSD on temperature [°C] (typ.)	Hysteresis temperature [°C] (typ.)
175	25

(8) Ground Wiring Pattern

When using both small signal and large current GND patterns, it is recommended to isolate the two ground patterns, placing a single ground point at the application's reference point so that the pattern wiring resistance and voltage variations caused by large currents do not cause variations in the small signal ground voltage. Be careful not to change the GND wiring pattern of any external components, either.

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